

Project 3:

The Optimize Control of Robotic Manipulator in Kinematics and Dynamics Aspect

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Project Description and Objectives:

The robot industry, which was represented by robotic manipulator, has made a great progress in development, which has led to the infiltration in all walks of life, and also played an increasingly significant role in them

operation not only improving the efficiency, but also saving massive costs, including time costs and energy costs. With the innovation on optimization control of robotic

In this project, describe the motion functions